

Behavioural Types for a Calculus of Concurrent Objects*

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Abstract

We present a new type system for TyCO, a name-passing calculus of concurrent objects. The system captures dynamic aspects of the behaviour of objects, namely non-uniform service availability. The notion of processes without errors is loosened, demanding only weak fairness in the treatment of messages.

1 Motivation

The role of name-passing process algebras in the study of the foundations of concurrent programming had been stressed by several authors (*cf.* [KY95, PT95]). The advantages of the object-oriented paradigm are also well known, and there are several proposals of name-passing calculus with such characteristics, as for example [Pie95]. In all of them one can find a static type system enjoying the subject-reduction property (invariance of a type under reduction) and having as corollary the absence of run-time errors for well-typed processes.

Types in object-oriented languages are “partial specifications of object’s behaviour”, and give information about the object’s interface; in name-passing process algebras types are used as a discipline for communication, and are assigned to names; in an object-oriented name-passing calculus names are possible locations of objects and the type of a name captures aspects of the object’s semantics.

In a setting where (active) concurrent objects are characterised by *non-uniform service availability* [Nie95], a static “types-as-interfaces” approach is not suitable to capture dynamic aspects of objects’ behaviours, namely the dependency of the objects’ interface from its internal state. We propose types as graphs (representing objects as state-transition systems), and demand weak fairness in the treatment of messages, in the sense that a request may be responded not immediately but sometime in the future. The paper presents a type system that is able to type objects with a non-uniform service availability, while preserving the subject-reduction property.

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A typical process not typable by “traditional” type systems [VH93, VT93, KY95, LW95] is a one-place buffer that only allows read operations when it is full, and write operations when it is empty.

$$\begin{aligned}\text{Empty}(b) &= b \triangleright [\text{write} : (u) \text{Full}(b u)] \\ \text{Full}(b u) &= b \triangleright [\text{read} : (r) r \triangleleft \text{val} : [u] \mid \text{Empty}(b)]\end{aligned}$$

The type systems mentioned above assign interface-like types to names. Therefore, name b should have a single interface, containing both methods’ labels write and read , and thus the example presented can not be typed. Nevertheless, the behaviour of the process (alternating between write and read operations) is very clear. Furthermore, a process containing the redex $\text{Empty}(b) \mid b \triangleleft \text{read} : [r]$ should not be considered an error, for the presence of a message $b \triangleleft \text{write} : [u]$ makes the reception of the read message possible.

The development of a type system able to type processes like the one above is the main motivation of this work.

2 The calculus of objects

TyCO (TYped Concurrent Objects) [VT93, Vas94] is an object-oriented name-passing calculus with asynchronous communication between concurrent objects via labelled messages carrying names. The calculus is developed along the trends of well-known models of concurrency, such as the π -calculus [Mil91, MPW92], the ν -calculus [HT91], and the actor model of computation [HBS73, Agh86].

2.1 Syntax

Consider *names* $u, v, x, y \in \mathcal{N}$, *labels* $a, b, c \in \mathcal{L}$, and *processes* $P, Q \in \mathcal{P}$. Let \tilde{v} stand for a sequence of names, and \tilde{x} for a sequence of pairwise distinct names.

Definition 2.1 The set \mathcal{P} of *processes* is given by the following grammar.

$$P ::= x \triangleright M \quad \mid \quad x \triangleleft m \quad \mid \quad P \mid Q \quad \mid \quad \nu x P \quad \mid \quad !x \triangleright M \quad \mid \quad \mathbf{0}$$

where $M \stackrel{\text{def}}{=} \sum_{i \in I} a_i : (\tilde{x}_i) P_i$ for I a finite index set, and $m \stackrel{\text{def}}{=} a : [\tilde{v}]$.

The basic processes are objects $x \triangleright M$, located at some name x and composed of a finite collection M of labelled methods (with pairwise distinct labels), and asynchronous labelled messages $x \triangleleft a : [\tilde{v}]$, targeted at some object’s location x and selecting the method a with actual parameters \tilde{v} . Each method $a : (\tilde{x}) P$ is labelled by a distinct label a , has formal parameters \tilde{x} and body P . The other constructors are the concurrent composition of processes, the restriction of the scope of a name to a process, the replication of objects, and the terminated process.

For typing purposes, we impose one important restriction on processes: the formal parameters \tilde{x} in a method $a : (\tilde{x}) P$ are not allowed to be locations of objects in the body P . Such a restriction is present in most object-oriented languages, where the creation of a new name and a new object are tightly coupled.

Notation 2.2 We abbreviate a method $a : () \mathbf{0}$ to a , and a process $\nu x_1 \cdots \nu x_n P$ to $\nu \tilde{x} P$.

Definition 2.3 An occurrence of a name x in a process P is *bound* if it is in a part of P with the form $a : (\tilde{u}x\tilde{y})Q$ or $\nu x Q$; otherwise the occurrence of x is *free*. The set $fn(P)$ of *free names* in a process P is defined accordingly, and so is *alpha-conversion*, denoted by \equiv_α . The process $P[\tilde{v}/\tilde{x}]$ denotes the simultaneous substitution of the free occurrences of \tilde{x} in P by \tilde{v} , defined only when \tilde{x} and \tilde{v} have the same length.

2.2 Operational semantics

Definition 2.4 *Structural congruence* is the smallest congruence relation over processes generated by the following rules.

$$\begin{aligned} P \equiv Q & \text{ if } P \equiv_\alpha Q \\ P \mid \mathbf{0} \equiv P & \quad P \mid Q \equiv Q \mid P \quad (P \mid Q) \mid R \equiv P \mid (Q \mid R) \\ \nu xy P \equiv \nu yx P & \quad \nu x \mathbf{0} \equiv \mathbf{0} \quad \nu x P \mid Q \equiv \nu x (P \mid Q) \text{ if } x \notin fn(Q) \end{aligned}$$

Definition 2.5 The result $M \bullet m$ of applying a communication m to a collection of methods M is the process $P[\tilde{v}/\tilde{x}]$ if m is of the form $a : [\tilde{v}]$ and $a : (\tilde{x})P$ is a method in M and the substitution is defined.

Definition 2.6 *One-step reduction* \rightarrow is the smallest relation over processes generated by the following rules.

$$\begin{array}{ll} \text{COM} & x \triangleright M \mid x \triangleleft m \rightarrow M \bullet m \\ \text{PAR} & P \mid R \rightarrow Q \mid R \text{ if } P \rightarrow Q \\ \text{STR} & P' \rightarrow Q' \text{ if } P' \equiv P, P \rightarrow Q, Q \equiv Q' \end{array} \quad \begin{array}{ll} \text{REP} & !x \triangleright M \mid x \triangleleft m \rightarrow !x \triangleright M \mid M \bullet m \\ \text{RES} & \nu x P \rightarrow \nu x Q \text{ if } P \rightarrow Q \end{array}$$

Reduction \twoheadrightarrow is the relation $\equiv \cup \rightarrow^+$, where \rightarrow^+ denotes the transitive closure of \rightarrow .

2.3 Error-processes

In order to deal with objects' non-uniform service availability we need to loosen the notion of process with error. The new concept of error requires two further notions.

Definition 2.7 A *context* \mathbf{C} is the concurrent composition of messages and a constant \square (called the *hole*).

Filling the hole of a context \mathbf{C} with a process P results in the process $\mathbf{C}[P]$.

Definition 2.8 1. A process P has a simple (respectively replicated) *x-redex* if $P \equiv \nu \tilde{u} (x \triangleright M \mid x \triangleleft m \mid Q)$ (respectively $P \equiv \nu \tilde{u} (!x \triangleright M \mid x \triangleleft m \mid Q)$).

2. A process P has a *bad x-redex* if P has an *x-redex* (simple or replicated) and $M \bullet m$ is not defined.

Definition 2.9 A process P is an *error*, notation $P \in \text{ERR}$, if

1. $\exists \mathbf{C} \mathbf{C}[P] \twoheadrightarrow Q$, and Q has a bad *x-redex*, for some x occurring in \mathbf{C} only has target of a message, and in a message that does not participate in the bad *x-redex*, then

2. $\forall_{\mathbf{C}, \mathbf{C}'[Q] \rightarrow R}$, and R has a bad x -redex, for some x occurring in \mathbf{C} only has target of a message, and in a message that does not participate in the bad x -redex.

Errors are processes with bad x -redexes that persist throughout reduction. A occasional bad x -redex is not enough to make the process an error. So, we give messages a chance to find their target, and therefore, we say that this calculus have weak fairness in the treatment of messages.

Example 2.10 *Error and non-error processes*

1. $S \stackrel{\text{def}}{=} \text{Empty}(x) \mid x \triangleleft \text{read}:[u] \notin \text{ERR}$ since, although the process S is a bad x -redex, we have $\mathbf{C}[S] \rightarrow \text{Full}(x \triangleright) \mid x \triangleleft \text{read}:[u]$, for $\mathbf{C} \stackrel{\text{def}}{=} x \triangleleft \text{write}:[v] \mid []$, containing no bad x -redexes;
2. $P \stackrel{\text{def}}{=} y \triangleright [b : x \triangleleft a] \mid !x \triangleright [c] \in \text{ERR}$, since $\mathbf{C}[P] \rightarrow !x \triangleright [c] \mid x \triangleleft a$ with $\mathbf{C} \stackrel{\text{def}}{=} y \triangleleft b \mid []$, and no context can undo the bad x -redex;
3. $Q \stackrel{\text{def}}{=} z \triangleright [e : (y) y \triangleleft a] \mid w \triangleright [l : !u \triangleright [c]] \notin \text{ERR}$, although we have $\mathbf{C}[Q] \rightarrow R$ with $R \stackrel{\text{def}}{=} !u \triangleright [c] \mid u \triangleleft a$ for $\mathbf{C} \stackrel{\text{def}}{=} z \triangleleft e : [u] \mid [] \mid w \triangleleft l$, and R is a persistent bad redex; however notice that u is in \mathbf{C} not has target of a message, what violates the condition in the definition, meaning that the environment is the generator of the error.

3 The type system

Processes are implicitly typed: although no type information is present in processes, it can be inferred by a type system that assigns type to names and sets of name-type pairs (called typings) to processes.

3.1 Types

A type is a *graph* whose nodes (states) can be interpreted as an object's interface and the arcs (transitions) as the invoked methods. The type of an object represents its possible life-cycles.

Definition 3.1 The set \mathcal{T} of *types* is inductively defined as follows.

1. $\mathcal{D} \subseteq \mathcal{T}$, for \mathcal{D} an initial algebra of some fixed data types;
2. $(V, I, A) \subseteq \mathcal{T}$, where V is a non-empty set of nodes, $I \subseteq V$ is a non-empty set of initial nodes, and $A \subseteq V \times (\mathcal{L} \times \mathcal{T}^*) \times V$ is a set of arcs labelled by $\mathcal{L} \times \mathcal{T}^*$. Graphs are directed and contain no isolated nodes. We further require that a graph with more than one initial node is the disjoint union of connected components, one for each initial node.

Notation 3.2 We use α, β, γ to denote types. For a given graph α , V_α denotes its set of nodes, I_α denotes its set of initial nodes, and A_α denotes its set of arcs; the label of an arc is denoted by t . Graphs are consider equal up to isomorphism on nodes.

We need also a notion of terminal nodes of a graph to define complete paths. A node is terminal if there are no arcs starting from it or otherwise the arcs end at an initial node.

Definition 3.3 The set T_α of *terminal nodes* of a graph α is the set

$$\{v \in V_\alpha \setminus I_\alpha \mid \nexists_{u \in V_\alpha} (v, t, u) \in A_\alpha, u \neq v\} \cup \{v \in V_\alpha \setminus I_\alpha \mid \exists_{u \in I_\alpha} (v, t, u) \in A_\alpha\}.$$

The union of graphs is a sum of behaviours. A graph that is the disjoint union of connected components represents a set of possible behaviours of an object, each behaviour represented by a connected subgraph.

Definition 3.4 The *union* $\alpha \uplus \beta$ of types α and β is the type γ such that

1. if α, β are graphs, then

$$\gamma \stackrel{\text{def}}{=} \begin{cases} (V_\alpha \cup V_\beta, I_\alpha \cup I_\beta, A_\alpha \cup A_\beta), & \text{if } V_\alpha \cap V_\beta = \emptyset \\ (V_\alpha \cup V_\beta, I_\alpha \setminus (V_\beta \setminus I_\beta) \cup I_\beta \setminus (V_\alpha \setminus I_\alpha), A_\alpha \cup A_\beta), & \text{otherwise;} \end{cases}$$

2. if $\alpha, \beta \in \mathcal{D}$ and $\alpha = \beta$, then $\gamma \stackrel{\text{def}}{=} \alpha$;
3. the union is undefined otherwise.

A graph that is the product of two graphs represents the joint behaviour (parallel composition or interleaving) of two objects located at a same name.

Definition 3.5 The *interleaving* $\alpha \parallel \beta$ of graphs α and β is the graph γ such that

1. $V_\gamma \stackrel{\text{def}}{=} V_\alpha \times V_\beta$, and $I_\gamma \stackrel{\text{def}}{=} I_\alpha \times I_\beta$, and
2. $A_\gamma \stackrel{\text{def}}{=} \{(uv, t, u'v) \mid \forall_{(u,t,u') \in A_\alpha} \exists_{v \in V_\beta}\} \cup \{(uv, t, uv') \mid \forall_{(v,t,v') \in A_\beta} \exists_{u \in V_\alpha}\}.$

Types abstract from objects' concrete behaviour: two different objects with equivalent behaviours have the same type. The equivalence relation is a pair of binary relations over types, one over the nodes of the graph and the other over the types labelling the graph's arcs.

Definition 3.6 *Bisimilarity on types.*

1. A symmetric binary relation $\mathcal{R} \subseteq V_\alpha \times V_\beta$ is a *bisimulation on graphs* (over a binary relation \mathcal{C} on types) if $\forall_{u \in V_\alpha} \forall_{v \in V_\beta}$ such that $u\mathcal{R}v$, if $(u, a : \tilde{\alpha}, u') \in A_\alpha$ then $\exists_{(v, \tilde{a}, \tilde{\beta}, v') \in A_\beta}$ with $u'\mathcal{R}v'$ and $\tilde{\alpha}\mathcal{C}\tilde{\beta}$ ¹.
2. Two nodes $u \in V_\alpha$, $v \in V_\beta$ are *bisimilar over \mathcal{C}* , denoted by $u \sim_{\mathcal{C}} v$, if there is a bisimulation \mathcal{R} over \mathcal{C} such that $u\mathcal{R}v$.

Compatibility of types.

1. A symmetric binary relation $\mathcal{C} \subseteq \mathcal{T} \times \mathcal{T}$ is a *type compatibility*, if $\alpha\mathcal{C}\beta$ implies $\forall_{u \in I_\alpha} \exists_{v \in I_\beta} u \sim_{\mathcal{C}} v$ ² when α, β are graphs, or $\alpha = \beta$ otherwise.
2. Two types α and β are *compatible*, denoted by $\alpha \sim \beta$, if there exists a type compatibility relation \mathcal{C} such that $\alpha\mathcal{C}\beta$.

¹Let $\alpha_1 \cdots \alpha_k \mathcal{C} \beta_1 \cdots \beta_k \stackrel{\text{def}}{=} \alpha_1 \mathcal{C} \beta_1 \wedge \cdots \wedge \alpha_k \mathcal{C} \beta_k$.

²This condition is enough to guaranty the bisimilarity of the graphs, since graphs do not have unreachable nodes.

The compatibility relation \sim is the largest type compatibility; thus, two graph types are compatible if all their nodes are bisimilar over the compatibility relation.

One can easily observe that \mathcal{T}/\sim specifies a class of process *behaviours*. Moreover, \sim is a congruence with respect to \parallel and \uplus .

Lemma 3.7 Suppose α, β and γ are graphs, and $\alpha \sim \beta$; then $(\alpha \parallel \gamma) \sim (\beta \parallel \gamma)$ and $(\alpha \uplus \gamma) \sim (\beta \uplus \gamma)$.

Proof 1. It is trivial to show the conditions of the definition, since the type constructor is simply a disjoint union.

2. The proof is standard; let $\mathcal{S} = \{((\alpha \parallel \gamma), (\beta \parallel \gamma)) \mid \alpha \sim \beta\}$; using the definition of \parallel it is straightforward to show that \mathcal{S} is a bisimulation on graphs. \blacksquare

Paths in graphs play an important role in our system. We compare types to know if a message can be accepted by an object.

Definition 3.8 *On paths of a graph.*

1. A *path* μ_α in a graph α is a chain of arcs in α of the form $(u_0, t_1, u_1), \dots, (u_{n-1}, t_n, u_n)$ with $n \geq 1$. We write $\mu_\alpha^{u,v}$ to denote the path starting at node u and ending at node v .
2. A path $\mu_\alpha^{u,v}$ is *complete* if $u \in I_\alpha$, and $v \in T_\alpha$ or $v \in I_\alpha$ if $\exists w \in T_\alpha (w, t, v) \in A_\alpha$.
3. For a path μ_α , a sequence of some of its arcs preserving the original ordering is called a *projection* of μ_α .

To characterise how graphs evolve with the reduction of processes we need the notion of subgraphs. This notion captures a transition relation on graphs.

Definition 3.9 A graph α is a *subgraph* of a graph β , denoted by $\alpha \leq \beta$, if $\alpha = \beta$ or $\exists u \in I_\beta (u, t, v) \in A_\beta$ with $v \in I_\alpha$ and each path of β starting in v is also a path of α .

The transitive closure of \leq is denoted by \leq^+ .

Lemma 3.10 If α, β, γ are graphs and $\alpha \leq^+ \beta$, then $(\alpha \parallel \gamma) \leq^+ (\beta \parallel \gamma)$.

Proof Let $u \in I_{(\beta \parallel \gamma)}$, $(u, t, v) \in A_{(\beta \parallel \gamma)}$, and suppose $t \in A_\beta$; then, by hypothesis, $v \in I_\alpha$ and each path of β starting in v is also a path of α ; since $t \in A_\beta$ then $v \in I_\gamma$ and by definition of \parallel , $v \in I_{\alpha \parallel \gamma}$, and the condition on the paths follows. \blacksquare

Notice that we do not have $\alpha \leq^+ \beta \Rightarrow (\alpha \uplus \gamma) \leq^+ (\beta \uplus \gamma)$, since no path starting in some element of I_α is a path of γ . But it is easy to show that $\alpha \leq^+ \beta \Rightarrow \alpha \leq^+ (\beta \uplus \gamma)$.

Types for replicated objects are obtained from a finite graph by means of a fix point operation.

Prop/Definition 3.11 *Replication of a graph.*

1. $\alpha_0 \stackrel{\text{def}}{=} (V_\alpha \setminus T_\alpha, I_\alpha, A_{\alpha_0})$, where

$$A_{\alpha_0} \stackrel{\text{def}}{=} \{(u, t, v) \mid (u, t, w) \in A_\alpha, \text{ and } v = w \text{ if } w \notin T_\alpha \text{ or } v = u \text{ otherwise}\}.$$

2. $\mathcal{F}(\alpha_0) = \uplus_{v \in V_{\alpha_0} \setminus I_{\alpha_0}} \alpha_0 \sigma_v \uplus \alpha_0$, and $\mathcal{F}(\alpha_{i+1}) = \uplus_{v \in V_{\alpha_i} \setminus V_{\alpha_{i-1}}} \alpha_0 \sigma_v \uplus \alpha_i$ with $i \geq 1$, where, for each $v \in V_{\alpha_i} \setminus V_{\alpha_{i-1}}$, σ_v is the substitution

$$\sigma_v \stackrel{\text{def}}{=} \begin{cases} I_{\alpha_0} \mapsto \{v\} \\ V_{\alpha} \setminus I_{\alpha} \mapsto \{w \mid \text{for each } u \in V_{\alpha} \setminus I_{\alpha}, w \text{ is fresh}\}. \end{cases}$$

3. The replication $\text{repl}(\alpha)$ of a finite graph α is the graph $\text{fix}(\mathcal{F}(\alpha_0))$.
4. One can easily see that \mathcal{F} is a continuous function since it is increasing by definition, and it is monotonous since if $\alpha_0 \subseteq \beta_0$ then $\mathcal{F}(\alpha_0) \subseteq \uplus_{v \in V_{\alpha_0} \setminus I_{\alpha_0}} \alpha_0 \sigma_v \uplus \beta_0 \subseteq \mathcal{F}(\beta_0)$ and, similarly, $\mathcal{F}(\alpha_i) \subseteq \mathcal{F}(\beta_i)$ for some $i \geq 1$.

3.2 Typings

The *name-usage-type* triple $x^* : \alpha$, with $*$ in $\{!, \downarrow, \uparrow\}$, is a formula denoting the assignment of type α to name x , location of an object (\downarrow), location of a replicated object ($!$), or destination of a message (\uparrow).

Definition 3.12 A *typing* Γ is a finite set of name-usage-type triples that has at most two occurrences of the same name, one as an object (replicated or not) and a second as a message.

Example 3.13 *Typing assignment*

1. The message $x \triangleleft a : \tilde{u}$ has a typing $\{x^\uparrow : (\{u_0, u_1\}, \{u_0\}, \{(u_0, a : \tilde{\alpha}, u_1)\}), \tilde{u} : \tilde{\alpha}\}$.

Graphically $\{x^\uparrow : \downarrow_{a:\tilde{\alpha}}, \tilde{u}:\tilde{\alpha}\}$, where \odot denotes an initial node.

2. The object $x \triangleright [a]$ has a typing $\{x^\downarrow : \downarrow_a\}$. The input-name x^\downarrow has the type

$\alpha_1 = \begin{array}{c} \odot \\ \swarrow \quad \searrow \\ \bullet \quad \bullet \end{array}$ in $x \triangleright [a + b]$, and $\alpha_2 = \begin{array}{c} \odot \\ a \downarrow \\ \bullet \\ b \downarrow \\ \bullet \end{array}$ in $x \triangleright [a : x \triangleright [b]]$.

3. The input-name x^\downarrow has the type $\beta = \begin{array}{c} \odot \\ a \downarrow \\ \bullet \\ \swarrow \quad \searrow \\ \bullet \quad \bullet \end{array}$ in $x \triangleright [a : x \triangleright [b + c]]$; the type

$\gamma = \begin{array}{c} \odot \\ \swarrow \quad \searrow \\ \bullet \quad \bullet \\ \swarrow \quad \searrow \quad \downarrow \quad \downarrow \\ \bullet \quad \bullet \end{array}$ in $x \triangleright [a : \text{if } y \text{ then } x \triangleright [b] \text{ else } x \triangleright [c]]$ ³, and the type

$\delta = \begin{array}{c} \odot \\ \swarrow \quad \searrow \\ \bullet \quad \bullet \\ \swarrow \quad \searrow \quad \downarrow \quad \downarrow \\ \bullet \quad \bullet \end{array}$, in $x \triangleright [a : \text{if } g \text{ then } x \triangleright [b] \text{ else } x \triangleright [b]]$.

³if y then P else $Q \stackrel{\text{def}}{=} \nu z (y \triangleleft \text{val} : z, z \triangleright [\text{true} : P + \text{false} : Q])$

Notice that we have $\beta \approx \gamma$, but $\alpha_2 \sim \delta$, as expected.

4. The input-name x^\dagger has the type $c \downarrow \begin{array}{c} \circ \\ \bullet \end{array} \quad \downarrow d \begin{array}{c} \circ \\ \bullet \end{array}$ in $y \triangleright [a : x \triangleright [c] + b : x \triangleright [d]]$; the graph is the union of two connected components, each one representing a possible behaviour of the name x .
5. Until now we have only dealt with messages and objects. The parallel composition of processes poses new problems.

The input-name x^\dagger has the type $\begin{array}{c} \circ \\ \swarrow a \quad \searrow b \\ \bullet \quad \bullet \\ \swarrow b \quad \nwarrow a \\ \bullet \end{array}$ in $x \triangleright [a] | x \triangleright [b]$, and the

type $\begin{array}{c} \circ \\ \swarrow a \quad \searrow b \\ \bullet \quad \bullet \\ \downarrow b \quad \downarrow a \\ \bullet \quad \bullet \end{array}$ in $x \triangleright [a : x \triangleright [b] + b : x \triangleright [a]]$. The first graph re-

sults from the interleaving of the graphs of the two objects. Intuitively, each path represents a possible sequence of actions. The types are bisimilar.

6. Replication has the consequence that graph types are no longer acyclic nor finite. The rule uses the greatest fix point of a function that, in each terminal node of a graph “hangs” that graph; for example, in $!x \triangleright [a : x \triangleright [b]]$, the input-name x^\dagger

have the type $\begin{array}{c} \circ \\ b \{ \bullet \}^a \\ \bullet \\ b \{ \bullet \}^a \\ \vdots \end{array}$.

Notation 3.14 Let $dom(\Gamma)$ be the set of the name-usage pairs in each triple of Γ ; then $\Gamma \cdot x^* : \alpha$ denotes the union of Γ and $\{x^* : \alpha\}$, provided $x^* \notin dom(\Gamma)$. For $x^* : \alpha \in \Gamma$ let $\Gamma(x^*) \stackrel{\text{def}}{=} \alpha$; let $\Gamma \setminus x^*$ denote the typing Γ without the occurrences of formulae with x^* . Let $\Gamma \upharpoonright P$ denote the restriction of Γ to the free names in P , and let $\Gamma[z/x]$ denote the result of replacing in Γ occurrences of x by the fresh name z .

If the parallel composition of two processes can lead to a persistent bad x -redex then the processes should not be composed. In this case we say that their respective typings are not compatible. But if the graphs of all output-names in a typing have some complete path that match with a projection of some path of the respective replicated input-name in the other typing, then there will be no persistent bad x -redexes and the typings are compatible.

Definition 3.15 Two typings Γ and Δ are *compatible*, denoted by $\Gamma \asymp \Delta$, if $\Gamma(x^\dagger)$ has a projection equal to some complete path of $\Delta(x^\dagger)$, and vice-versa.

We now extended the notions of union and interleaving of types to typings.

Definition 3.16 The *union* $\Gamma \uplus \Delta$ of two typings is the typing:

1. $\Gamma \cup \Delta$, if $\text{dom}(\Gamma) \cap \text{dom}(\Delta) = \emptyset$;
2. $(\Gamma \cdot x^* : \gamma) \uplus (\Delta \setminus x^*)$, if $\Gamma(x^*) = \alpha$, $\Delta(x^*) = \beta$, and $\gamma \stackrel{\text{def}}{=} \begin{cases} \alpha, & \text{if } \alpha \sim \beta \\ \alpha \uplus \beta, & \text{otherwise;} \end{cases}$
3. $\{x^* : \alpha, x^\dagger : \beta\} \cup ((\Gamma \setminus x^*) \uplus (\Delta \setminus x^\dagger))$, if $\Gamma(x^*) = \alpha$, $\Delta(x^\dagger) = \beta$, and $* \in \{\dagger, \downarrow\}$;
4. $\{x^\dagger : \alpha\} \cup ((\Gamma \setminus x^\dagger) \uplus (\Delta \setminus x^\dagger))$, if $\Gamma(x^\dagger) = \alpha$, $\Delta(x^\dagger) = \beta$, and $\alpha = \text{repl}(\gamma)$, for some γ such that $\gamma \sim \beta$;
5. $\{x^\dagger : \alpha, x^\downarrow : \beta\} \cup ((\Gamma \setminus x^\dagger) \uplus (\Delta \setminus x^\downarrow))$, if $\Gamma(x^\dagger) = \alpha$ and $\Delta(x^\downarrow) = \beta$.

Definition 3.17 The *interleaving* $\Gamma \parallel \Delta$ of two typings is the typing:

1. $\Gamma \cup \Delta$, if $\text{dom}(\Gamma) \cap \text{dom}(\Delta) = \emptyset$;
2. $(\Gamma \cdot x^* : \gamma) \parallel (\Delta \setminus x^*)$, if $\Gamma(x^*) = \alpha$, $\Delta(x^*) = \beta$, and $\gamma \stackrel{\text{def}}{=} \begin{cases} \alpha \parallel \alpha, & \text{if } \alpha \sim \beta \\ \alpha \parallel \beta, & \text{otherwise;} \end{cases}$
3. $\{x^* : \alpha, x^\dagger : \beta\} \cup ((\Gamma \setminus x^*) \parallel (\Delta \setminus x^\dagger))$, if $\Gamma(x^*) = \alpha$, $\Delta(x^\dagger) = \beta$, and $* \in \{\dagger, \downarrow\}$;
4. $\{x^\dagger : \alpha\} \cup ((\Gamma \setminus x^\dagger) \parallel (\Delta \setminus x^\dagger))$, if $\Gamma(x^\dagger) = \alpha$, $\Delta(x^\dagger) = \beta$, and $\alpha = \text{repl}(\gamma)$, for some γ such that $\gamma \sim \beta$;
5. $\{x^\dagger : \alpha, x^\downarrow : \beta\} \cup ((\Gamma \setminus x^\dagger) \parallel (\Delta \setminus x^\downarrow))$, if $\Gamma(x^\dagger) = \alpha$ and $\Delta(x^\downarrow) = \beta$.

In the two definitions above, the rules should always be tried in the order presented.

Definition 3.18 $\text{repl}(\Gamma) \stackrel{\text{def}}{=} \{x^* : \text{repl}(\Gamma(x^*)) \mid \forall_{x^* \in \text{dom}(\Gamma)}\}$, and $* \in \{\downarrow, \uparrow\}$.

The notion of subgraph naturally extends to typings.

Definition 3.19 Let $\Delta \leq \Gamma$ if $\text{dom}(\Delta) \subseteq \text{dom}(\Gamma)$ and $\forall_{x^* \in \text{dom}(\Delta) \cap \text{dom}(\Gamma)} \Delta(x^*) \leq \Gamma(x^*)$.

Lemma 3.20 If $\Delta \leq \Gamma$ and $\Gamma \simeq \Lambda$, then $(\Delta \parallel \Lambda) \leq (\Gamma \parallel \Lambda)$.

Proof Follows from the definitions of \parallel and \leq for typings, using lemma 3.11. ■

3.3 Typing assignment system

We finally present the static typing assignment system. It has an axiom or a rule for each constructor of the calculus, plus a weak rule allowing to add a new output-name to a typing.

Definition 3.21 A *typing assignment* is a formula $\Gamma \vdash P$, for any process P and typing Γ . If such a formula is provable using the axiom and rules presented below we say that P is *well-typed* under typing Γ .

Definition 3.22 (Behavioural type system) The typing assignment system is inductively defined by the following axioms and rules.

$$\text{NIL} \quad \emptyset \vdash \mathbf{0}$$

$$\text{MSG} \quad \{\tilde{u}^* : \tilde{\alpha}, x^\dagger : (\{v_0, v_1\}, \{v_0\}, \{(v_0, a : \tilde{\alpha}, v_1)\})\} \vdash x \triangleleft a : [\tilde{u}] \quad (v_0 \neq v_1)$$

$$\text{OBJ} \quad \frac{\Gamma_i \cdot \tilde{x}_i^\dagger : \tilde{\alpha}_i \vdash P_i}{\bigoplus_{i \in I} (\Gamma_i \setminus x^\dagger) \uplus \{x^\dagger : \alpha\} \vdash x \triangleright \sum_{i \in I} a_i : (\tilde{x}_i) P_i} \quad (1)$$

$$\text{REP} \quad \frac{\Gamma \vdash x \triangleright M}{\text{repl}(\Gamma) \vdash !x \triangleright M} \quad (2) \quad \text{RES} \quad \frac{\Gamma \vdash P}{\Gamma \setminus x \vdash \nu x P}$$

$$\text{PAR} \quad \frac{\Gamma \vdash P \quad \Delta \vdash Q}{\Gamma \parallel \Delta \vdash P, Q} \quad (\Gamma \simeq \Delta) \quad \text{WEAK} \quad \frac{\Gamma \vdash P}{\Gamma \cdot x^\dagger : \alpha \vdash P}$$

(1) α is such that $I_\alpha \stackrel{\text{def}}{=} \{u\}$ for u a fresh node, and

$$A_\alpha = \bigcup_{i \in I} \{(u, a_i : \tilde{\alpha}_i, w) \mid x^* \notin \text{dom}(\Gamma_i) \text{ and } w \text{ is fresh}\} \cup \\ \bigcup_{i \in I} \{(u, a_i : \tilde{\alpha}_i, v) \mid x^* \in \text{dom}(\Gamma_i) \text{ and for each } v \in I_{\Gamma_i(x^*)}\} \cup \\ \bigcup_{i \in I} A_{\Gamma_i(x^*)}$$

for $* \in \{\uparrow, \downarrow\}$.

(2) $(\simeq_{i \in I} (\Gamma_i \setminus x^\dagger)) \simeq \{x^\dagger : \text{repl}(\Gamma(x^\dagger))\}$, where I is the index set of M .

In the following we give a short description of the rules in the behavioural type system.

NIL: the terminated process has an empty typing;

MSG: the graph of a message has a single arc labelled with the message's label to the target, and to the carried names are assign arbitrary types;

OBJ: the graph of an object has as many arcs starting from the initial node as the number of initial nodes of its type in each of its methods. Each arc is labelled with the methods's label. In the ending node of each of those arcs we hang the graph of that object as it occurs in the corresponding method;

REP: the type of a replicated object is the greatest fix-point of the graph of the object;

PAR: the parallel composition of two processes has a typing resulting from the interleaving of the components' typings;

RES: bounded names are removed from the typing;

WEAK: one can add to the typing of a process a type assignment formula with an output-name that does not occur in the typing.

3.4 Some properties of the type system

The main theorem is subject-reduction, with the corollary that guarantees absence of runtime errors in well-typed processes. Another important result is the uniqueness of the type assignment to each free name in a well-typed process.

In order to show that this properties, we need some auxiliary results.

Lemma 3.23 (Typing Lemma) If $\Gamma \vdash P$, then

1. $fn(P) \subseteq dom(\Gamma)$,
2. if $x \notin fn(P)$ then $\Gamma \setminus x^* \vdash P$,
3. $\Gamma \upharpoonright P \vdash P$.

Proof By induction on the length of the deduction of $\Gamma \vdash P$. ■

Lemma 3.24 (Typability of Subterms) If $\Gamma \vdash P$ and Q is a subterm of P , then $\exists_{\Delta} \Delta \vdash Q$.

Proof By induction on the structure of P . ■

Lemma 3.25 (Substitution Lemma) If $\Gamma \vdash P$ and $\Gamma(z^*) \sim \Gamma(\tilde{x}^*)$ then $\Gamma \setminus \tilde{x}^* \vdash P[\tilde{z}/\tilde{x}]$.

Proof By substitution of z for x in the deduction. The substitution results in a new instance of each axiom or rule, and the side conditions in the OBJ-rule and PAR-rule are preserved: if $\Gamma \asymp \Delta$ then $\Gamma[\tilde{z}/\tilde{x}] \asymp \Delta[\tilde{z}/\tilde{x}]$. ■

Lemma 3.26 (Congruence Lemma) If $\Gamma \vdash P$ and $P \equiv Q$, then $\Gamma \vdash Q$.

Proof By a simple case analysis on the rules defining \equiv . ■

Theorem 3.27 (Subject-reduction) If $\Gamma \vdash P$ and $P \twoheadrightarrow Q$, then $\exists_{\Delta} \Delta \vdash Q$ and $\Delta \leq \Gamma$.

Proof By induction on \twoheadrightarrow . If the reduction ends with the STR-rule or $P \equiv Q$ then use the congruence lemma. The non-trivial cases are when reduction ends with the PAR-rule and the COM-axiom (REP is similar to COM).

If reduction ends with the RES-rule let $P \equiv \nu x P'$ and $Q \equiv \nu x Q'$; by typability of subterms $\exists_{\Gamma'} \Gamma' \vdash P'$ and by hypothesis of the RES-rule $P' \twoheadrightarrow Q'$; then by the induction hypothesis $\exists_{\Delta'} \Delta' \vdash Q'$ and $\Delta' \leq \Gamma'$; by lemma 3.22.2 we have $\Gamma \setminus x^* \vdash P'$; if $x \in fn(P)$ then $\Gamma' = \Gamma \cdot x^*$ else $\Gamma' = \Gamma$, and Δ' is defined similarly; since $\Delta' \leq \Gamma'$ then $\Delta \leq \Gamma$.

If reduction ends with the PAR-rule let $P \equiv P' \mid R$ and $Q \equiv Q' \mid R$; by typability of subterms $\exists_{\Gamma', \Lambda} \Gamma' \vdash P'$ and $\Lambda \vdash R$ with $\Gamma = \Gamma' \parallel \Lambda$, and by induction hypothesis $\exists_{\Delta'} \Delta' \vdash Q'$ and $\Delta' \leq \Gamma'$. The result follows by lemma 3.20.

If reduction ends with the COM-axiom let $P \equiv x \triangleright M \mid x \triangleleft m$. By the PAR-rule and by typability of subterms $\Gamma = \Gamma' \parallel \Delta'$ with $x^\perp : \alpha \in \Gamma'$ and $x^\perp : \beta \in \Delta'$; if $M \bullet m$ is undefined then $\Delta = \Gamma$ else by the induction hypothesis and by the substitution lemma we have $\exists_{\Delta} \Delta \vdash M \bullet m$ ($\Delta = \Gamma_i \cdot \tilde{x}_i^\dagger[\tilde{v}/\tilde{x}] \vdash M \bullet m$, being \tilde{v} the sequence of names in m), and by the OBJ-rule if $x^\perp \in dom(\Delta)$ then $\Delta(x^\perp) \leq \alpha$, and if $x^\perp \in dom(\Delta)$ then $\Delta(x^\perp) \leq \beta$; it follows that $\Delta \leq \Gamma$. ■

Corollary 3.28 If P is well-typed then $P \notin \text{ERR}$.

Proof Suppose P is well-typed and $P \in \text{ERR}$. By definition of ERR , P has $!x \triangleright M$ and $x \triangleleft m$ as subterms, both typable by typability of subterms, with compatible types. Therefore, $M \bullet m$ is defined, and then it is not a persistent bad x -redex; we have reached an absurd, since, by hypothesis, $P \in \text{ERR}$. ■

The system enjoys the property of *uniqueness* of the types assigned to the free names in a process.

Proposition 3.29 If $\Gamma \vdash P$ and $\Delta \vdash P$ then $\Gamma \upharpoonright P = \Delta \upharpoonright P$.

Proof By a case analysis of the rules defining the type system, noting that, with the exception of the WEAK -rule, each rule defines one and only one typing for a process, up to renaming of nodes. ■

4 Conclusions and discussion

This paper presents a new type system for TYPed Concurrent Objects. The type system captures dynamic aspects of objects’ behaviour, namely non-uniform service availability. Types are graphs, and the type compatibility relation is a bisimulation. We propose a new notion of error-process: the persistence of bad x -redexes. Thus, processes without errors have weak fairness in the treatment of messages. The type system enjoys the subject-reduction property.

The presented type system types all processes the previous system [VT93] does, except for those that do not conform to the restriction in section 2. The buffer-cell in section 1 constitutes an example of a process this system types while the does previous not. Nevertheless some “basic” mistakes (like typing $puhs$ instead of $push$ in the process $x \triangleright [push : (w) P] \mid x \triangleleft puhs : [v]$), are no longer detected as error-processes.

The starting point for this work are the ideas of Nierstrasz on regular types for active objects. Puntigam also starts from Nierstrasz work, and uses terms of a process algebra (without name-passing) as types [Pun95, Pun96]. His work is centred on subtyping, and not on type assignment systems. There is now a lot of work on types for mobile processes but, up to our knowledge, the only work in the context of mobile processes where types are graph seems to be Yoshida’s [Yos96]. Her graphs give information about the deterministic behaviour of a process; our graphs are inspired on Milner’s derivation trees [Mil89].

This work is still in a preliminary stage; a lot of work has yet to be done. The points requiring further study include:

1. the proof of the conjecture that the typing assignment is decidable and the typing inference is computable.
2. an algebraic version of the notion of types, more tractable since types will be syntactic. A labelled transition system for processes can easily be defined, leading to a behavioural equivalence on processes.

3. the application of this type system to some object-oriented programming language.
4. the interpretation of types with a temporal logic and the definition of a type-theory.

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